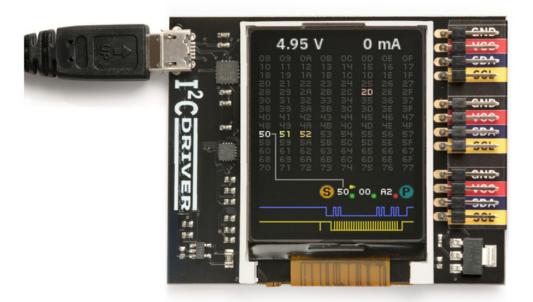
i2cdriver

Contents:

1	Syste	System Requirements				
	1.1	Installation	:			
	1.2	Quick start	:			
	1.3	Module Contents	4			
Ind	dex		,			



 I^2 CDriver is an easy-to-use, open source tool for controlling I^2 C devices over USB. It works with Windows, Mac, and Linux, and has a built-in color screen that shows a live "dashboard" of all the I^2 C activity.

The $I^2CDriver$ User Guide has complete information on the hardware:

https://i2cdriver.com/i2cdriver.pdf

Contents: 1

2 Contents:

CHAPTER 1

System Requirements

Because it is a pure Python module, i2cdriver can run on any system supported by pyserial. This includes:

- Windows 7 or 10
- Mac OS
- Linux, including all Ubuntu distributions

Both Python 2.7 and 3.x are supported.

1.1 Installation

The i2cdriver package can be installed from PyPI using pip:

```
$ pip install i2cdriver
```

1.2 Quick start

To connect to the I2CDriver and scan the bus for connected devices:

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To read the temperature in Celsius from a connected LM75 sensor:

```
>>> d=i2cdriver.EDS.Temp(i2c)
>>> d.read()
17.875
>>> d.read()
18.0
```

The User Guide at https://i2cdriver.com has more examples.

1.3 Module Contents

class i2cdriver.I2CDriver (port='/dev/ttyUSBO', reset=True)
 A connected I2CDriver.

Parameters

- port (str) The USB port to connect to
- reset (bool) Issue an I2C bus reset on connection

After connection, the following object variables reflect the current values of the I2CDriver. They are updated by calling <code>getstatus()</code>.

Variables

- **product** product code e.g. 'i2cdriver1' or 'i2cdriverm'
- **serial** serial string of I2CDriver
- uptime time since I2CDriver boot, in seconds
- voltage USB voltage, in V
- current current used by attached device, in mA
- temp temperature, in degrees C
- scl state of SCL
- sda state of SDA
- **speed** current device speed in KHz (100 or 400)
- mode IO mode (I2C or bitbang)
- pullups programmable pullup enable pins
- ccitt_crc CCITT-16 CRC of all transmitted and received bytes

setspeed(s)

Set the I2C bus speed.

Parameters s (int) – speed in KHz, either 100 or 400

setpullups(s)

Set the I2CDriver pullup resistors

Parameters s – 6-bit pullup mask

scan (silent=False)

Performs an I2C bus scan. If silent is False, prints a map of devices. Returns a list of the device addresses.

reset()

Send an I2C bus reset

start (dev, rw)

Start an I2C transaction

Parameters

- dev 7-bit I2C device address
- **rw** read (1) or write (0)

To write bytes [0x12, 0x34] to device 0x75:

```
>>> i2c.start(0x75, 0)
>>> i2c.write([0x12,034])
>>> i2c.stop()
```

read ()

Read I bytes from the I2C device, and NAK the last byte

write(bb)

Write bytes to the selected I2C device

Parameters bb – sequence to write

stop()

stop the i2c transaction

regrd (dev, reg, fmt='B')

Read a register from a device.

Parameters

- dev 7-bit I2C device address
- **reg** register address 0-255

1.3. Module Contents 5

• fmt - struct.unpack() format string for the register contents, or an integer byte count

If device 0x75 has a 16-bit unsigned big-endian register 102, it can be read with:

```
>>> i2c.regrd(0x75, 102, ">H")
4999
```

```
regwr (dev, reg, vv)
```

Write a device's register.

Parameters

- dev 7-bit I2C device address
- reg register address 0-255
- **vv** value to write. Either a single byte, or a sequence

To set device 0x34 byte register 7 to 0xA1:

```
>>> i2c.regwr(0x34, 7, 0xa1)
```

If device 0x75 has a big-endian 16-bit register 102 you can set it to 4999 with:

```
>>> i2c.regwr(0x75, 102, struct.pack(">H", 4999))
```

monitor(s)

Enter or leave monitor mode

Parameters s - True to enter monitor mode, False to leave

getstatus()

Update all status variables

```
class i2cdriver.START (addr, rw, ack)
class i2cdriver.STOP
class i2cdriver.BYTE (b, rw, ack)
```

Index

```
В
BYTE (class in i2cdriver), 6
G
getstatus() (i2cdriver.I2CDriver method), 6
I2CDriver (class in i2cdriver), 4
M
monitor() (i2cdriver.I2CDriver method), 6
R
read() (i2cdriver.I2CDriver method), 5
regrd() (i2cdriver.I2CDriver method), 5
regwr () (i2cdriver.I2CDriver method), 6
reset() (i2cdriver.I2CDriver method), 5
S
scan () (i2cdriver.I2CDriver method), 5
setpullups() (i2cdriver.I2CDriver method), 5
setspeed() (i2cdriver.I2CDriver method), 4
START (class in i2cdriver), 6
start() (i2cdriver.I2CDriver method), 5
STOP (class in i2cdriver), 6
stop() (i2cdriver.I2CDriver method), 5
W
write() (i2cdriver.I2CDriver method), 5
```